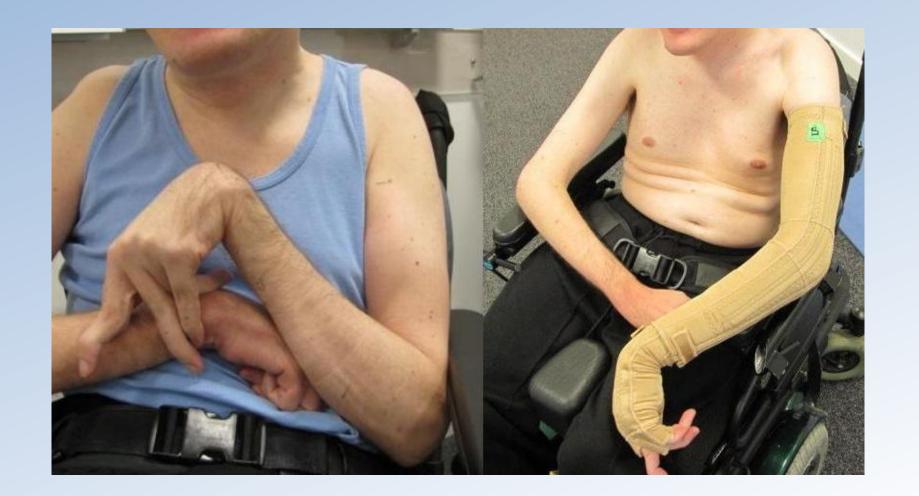
Background

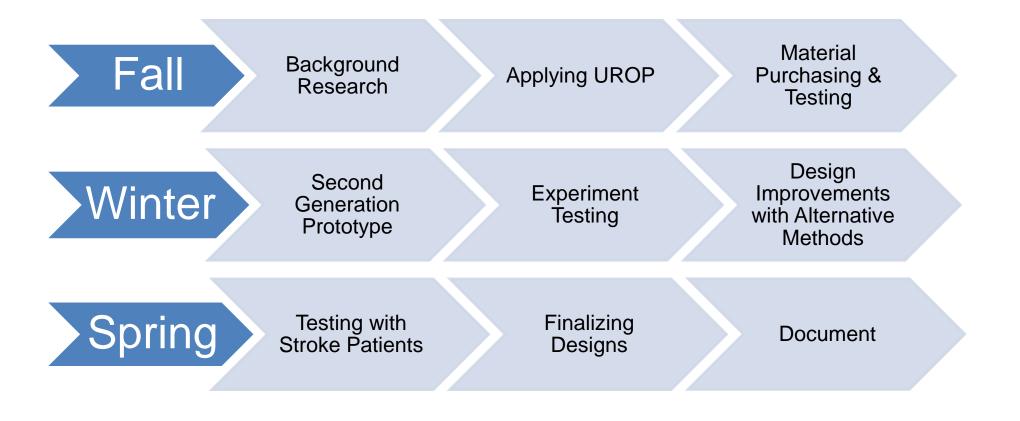
With the frequency of stroke occurring is increasing, there is a higher need to provide a more efficient and effective rehabilitation method. There are already previous research done using robotic therapy on patients that suffer a stroke.



Goals and Objectives

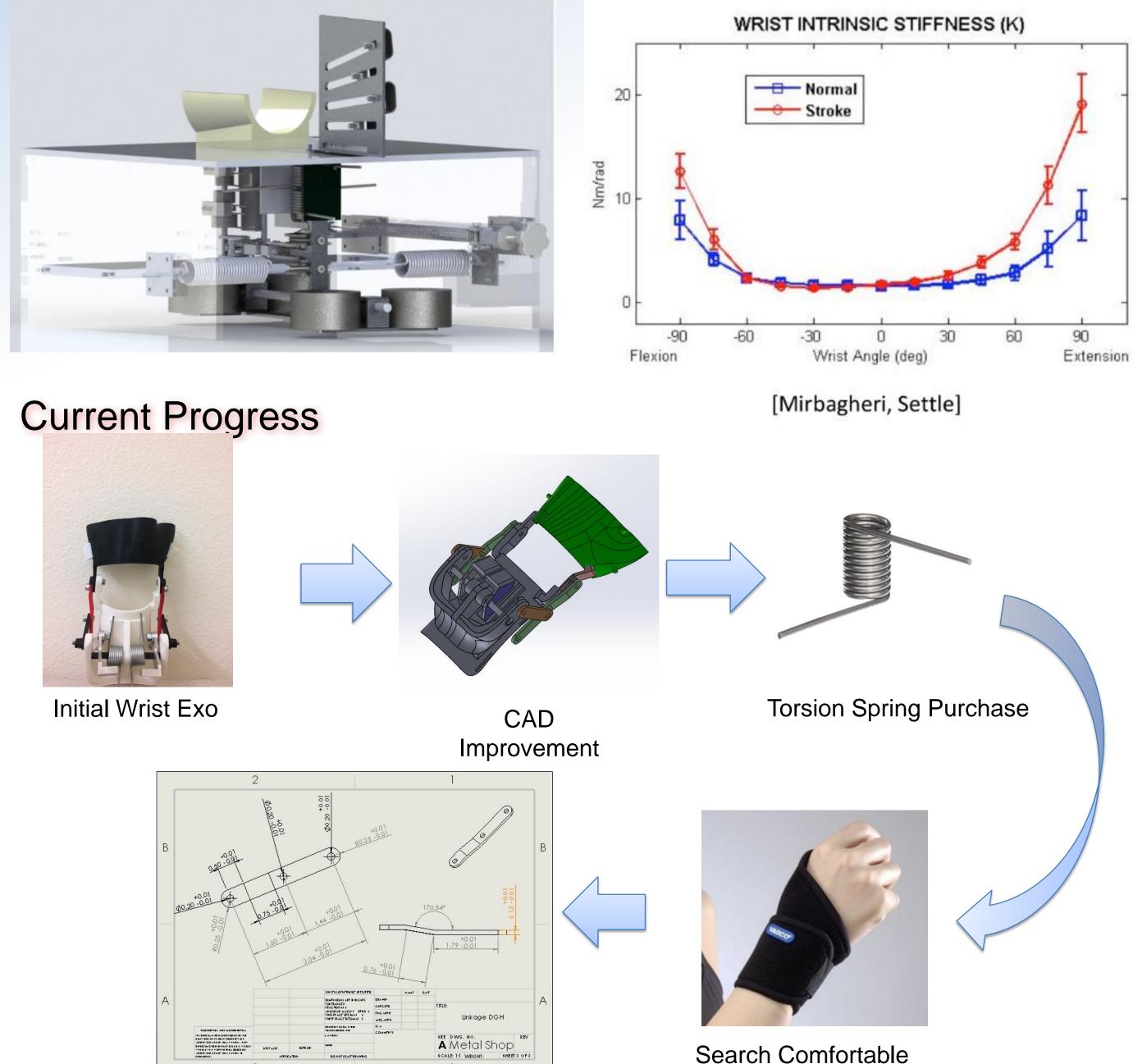
The goal of our project is to create a stand-alone wearable device using scaled down linkages to aid patient with movement in their daily lives. We are creating a wrist exoskeleton made with mostly 3D print and some metal parts. The main objective is to make a durable, strong, and light wrist exoskeleton so the patient can wear it freely.

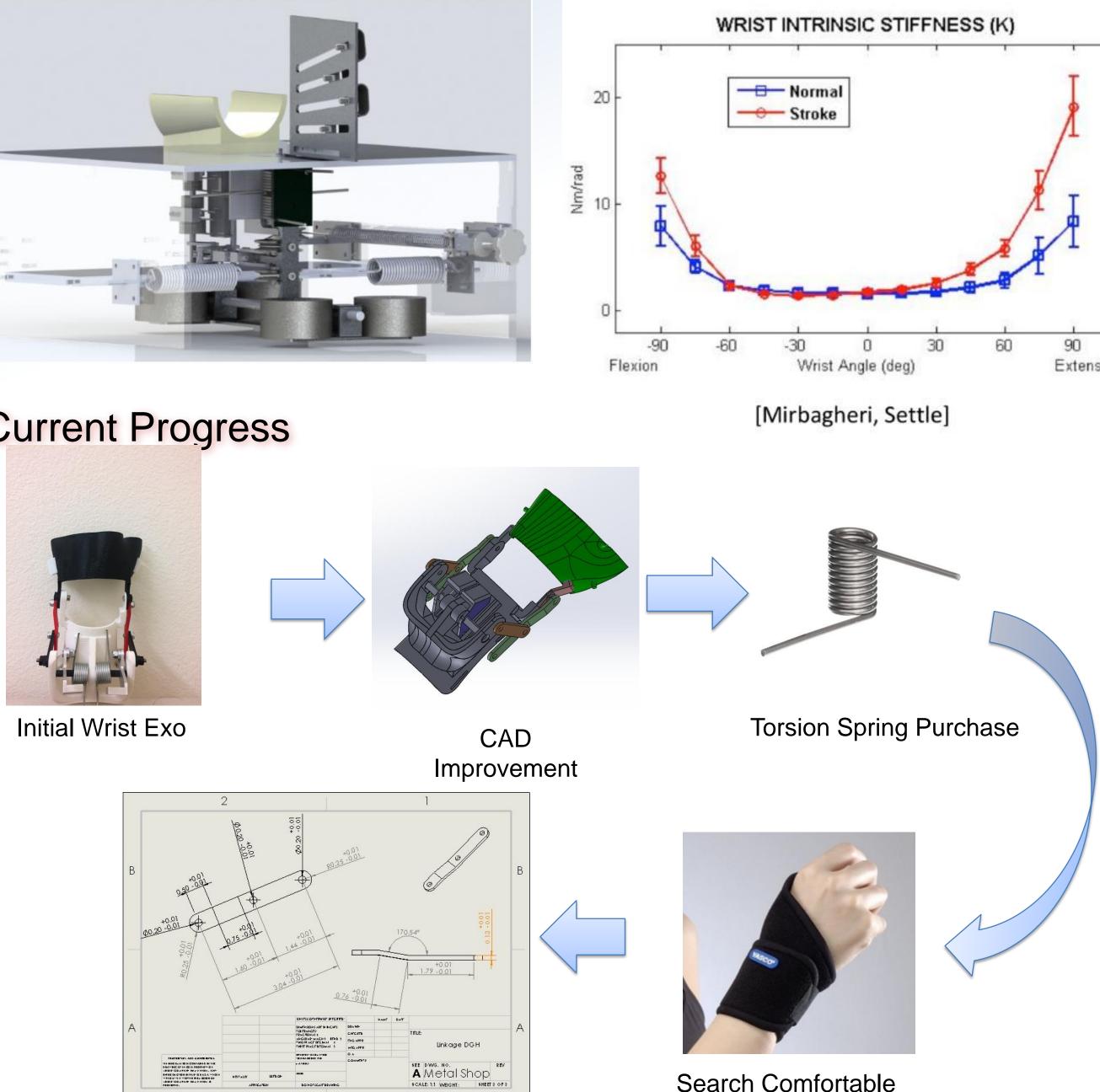
Project Timeline



Previous Model & Study

A previous study done by a doctoral student at UCI, developed a mechanism called WRIST. The purpose of the machine is to use a combination of torsional, linear springs, and linkages to create resonance with the system to aid the patient in moving their wrist. When a system operates at resonant frequency, it amplifies the movement. Using this concept, WRIST allowed stroke patients to gain more mobility on their wrist.





Pads to cover the wrist

Wrist Exoskeleton

Robotic Rehabilitation – Release, Rehabilitation, Remobilization Advisor: Professor David Reinkensmeyer, Ph. D

Manufacturing Linkages



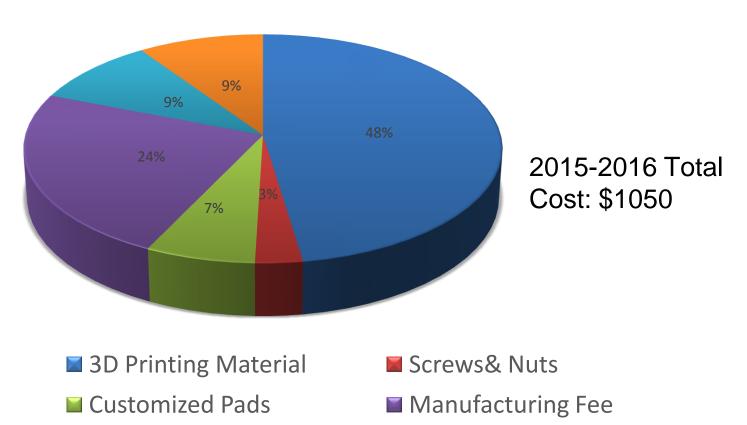


Future Work

We already figure out the old prototype's weaknesses and have all the CAD files ready to be 3-D printed. Some components are adjusted to make sure the physical mechanism work perfectly. We are currently in the process of working with the manufacturer about 3-D materials, torsional springs, and paddings. In the winter, all components will be 3-D printed and tested to be a commercial product.



2015-2016 Wrist Exoskeleton Budget



Other Manufacturing Tools

Team Member



Torrsion Spring



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Xinyi Fan

